

JAVAD

TRIUMPH-LS



TRIUMPH-LS

Receiver+Antenna+Radio Modem+Controller+Pole



complete
RTK receiver system
\$ 8,640

Prices are F.O.B San Jose, California.
Shipping, insurance and other charges apply

See www.javad.com for details



Wake up to the new world! Introducing the TRIUMPH-LS

Javad,
Just a note of appreciation. Thank you for implementing so many of my requests. We're doing real work with this receiver: boundary, topographic and staking. The staking routines are very productive. Every release of the software gets better and better. The hardware is solid, showing great promise in a range of environments. I was skeptical of the all-in-one box approach, but you are winning me over every time I take it out. You're breaking new ground and this system is unlike anything I've ever used.

Shawn Billings
Billings Surveying and Mapping Company



So easy my 12 year old can do it.

Matthew D. Sibole, PLS

- The adjustable and telescoping pole is lightweight and easy to collapse. This will make it easy to **walk through woods** and put into a car to drive around.
- The built in compass makes it **very easy to stake out** points. The stakeout screen points you in the right direction and gives you the distance to the point.
- Long battery life (**24 hours**)
- It seems to fix reliably in locations where **other receivers would stand a slim chance of fixing.**

Matt Johnson, PE



Here are some photos of my boys helping me survey out in the desert yesterday.

Jack M. Smith

I worked with the TRIUMPH-LS and Triumph-2 today for a few hours. I was impressed with the ability to get a good repeatable fix in pretty thick tree cover.

I also was able to localize on an assumed coordinate system without too much trouble. I don't do this very often but was able to localize three times today (2 times just to write down try and memorize the process).

Matthew Siobel, PLS



Drop Test



See video at www.javad.com

VICTOR-LS



Rugged
hand-held controller
with J-Field
application software.

See www.javad.com for details